

Behavioural Type Systems

Algorithms Analysing Algorithms

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Plan

- Behavioural
- Type Systems:
- Algorithms Analysing
- Algorithms

Behavioural Properties

“Behavioural Type Systems: Algorithms Analysing Algorithms”

```

public PType prod(PType that) throws IllegalArgumentException {
    Map n = Tools.union(this.names,that.names);
    Map nli = new HashMap(), // new local inputs
        nlo = new HashMap(), // new local outputs
        nri = new HashMap(), // new remote inputs
        nro = new HashMap(); // you probably got the idea by :

    Mult al,ar,bl,br,m; // names as in Mult.radd
    for (Iterator i = n.keySet().iterator();i.hasNext();) {
        Var v = (Var)i.next();
        al = this.getMult(true, v,true);
        ar = this.getMult(false,v,true);
        bl = that.getMult(true, v,true);
        br = that.getMult(false,v,true);
    }
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Behavioural Properties

- Deadlock-freedom
- Termination
- Isolation
- Determinism

Determinism Examples

Deterministic System: Coffee Machine



Non-Deterministic System: Printer

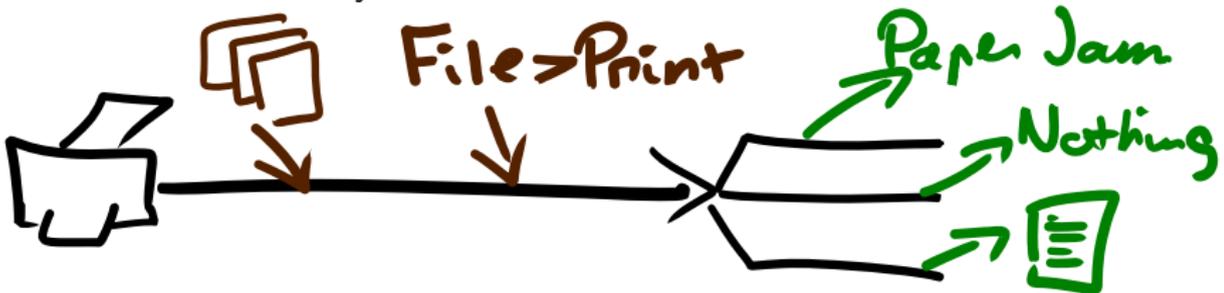


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Behavioural Types

“Behavioural **Type Systems: Algorithms** Analysing Algorithms”

Who provides the types?

- *Type Checking*: The programmer
- *Type Inference*: The type system

When to type?

- *Static Analysis*: “Compile time”
- *Dynamic Checking*: Run time

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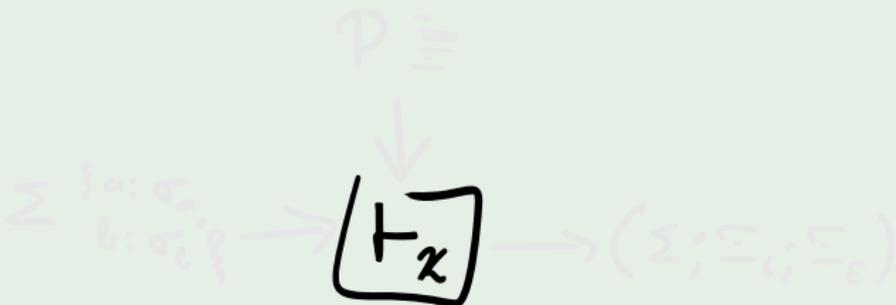
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Type Systems

Finding/Verifying properties without running the program

My Type Inference System



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$$P \equiv$$

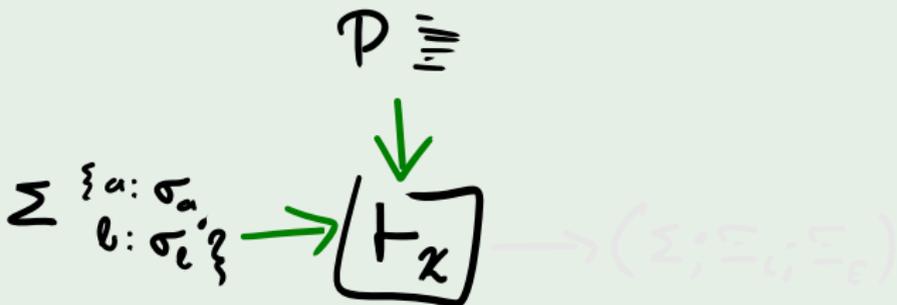

$$\vdash_{\mathcal{R}}$$

$$\Sigma \vdash \sigma \rightarrow (\Sigma; \Sigma_C; \Sigma_E)$$

Type Systems

Finding/Verifying properties without running the program

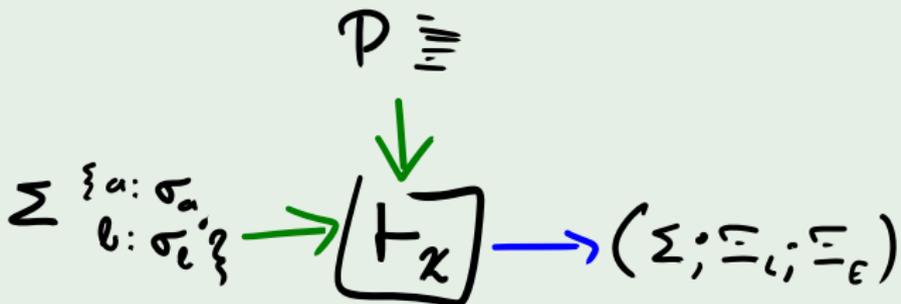
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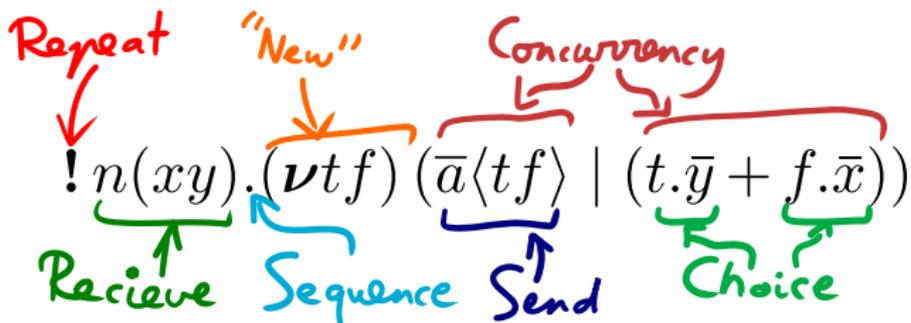
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Process Calculi

“Behavioural Type Systems: Algorithms Analysing Algorithms”

The π -calculus: a tiny concurrent “programming language”.



Dependency Analysis (1)

“Behavioural Type Systems: Algorithms **Analysing** Algorithms”

- *Parallel composition* fundamental to the π -calculus

$$P = P_1 \mid P_2 \mid \dots \mid P_n$$

- Need to analyse one component at a time

$$\{\Gamma_i \vdash P_i\} \mapsto (\Gamma \vdash P)$$

- Need to make assumptions on the *environment*

$$\Gamma_i = (\Xi_L \blacktriangleleft \Xi_E)$$

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Dependency Analysis (2)

Definition (Behavioural Statements)

$$\Xi ::= (\gamma \triangleleft \Xi) \quad | \quad (\Xi \vee \Xi) \quad | \quad (\Xi \wedge \Xi) \quad | \quad \top \quad | \quad \perp$$

$$a_{\mathbb{D}} \triangleleft (b_{\mathbb{D}} \wedge c_{\mathbb{D}}) \quad \vdash \quad A = ! a(tf). \bar{b}(\nu t' f'). (t'. \bar{c} \langle tf \rangle + f'. \bar{f})$$

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Generic Type Systems

Captures the essence of dependency analysis

Can be *instantiated*:

- Write *semantic goals*
- Rules *parametrised by elementary rules*

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Summary

- Behavioural Properties
- Type Inference Systems: Find properties automatically
- The π -calculus: A simple programming language
- Dependency Analysis: Reusable types for reusable code
- Generic Type Systems: Write an elementary rule, get a type system for free

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Thank You

Answers to questions are non-isolated, non-deterministic, non-uniform, active, responsive, deadlock-free, and terminate.

Supplementary Material

▸ Types & Multiplicities

▸ Choice

▸ Algebra

▸ Semantics

▸ Type Systems

▸ Properties

▸ Soundness

▸ Future Work

Types & Multiplicities

Behavioural Statements Δ, Ξ, \dots

$\Delta ::=$

$\Delta \vee \Delta \quad | \quad \Delta + \Delta \quad | \quad \Delta \wedge \Delta \quad | \quad \Delta \triangleleft \Delta \quad | \quad p_k \quad | \quad \perp \quad | \quad \top \quad | \quad p^m$

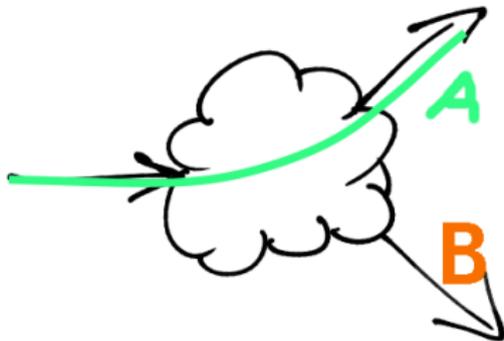
Multiplicities

$m ::= 0 \quad | \quad 1 \quad | \quad \omega \quad | \quad \star$

Choice

Definition (Selection $A \vee B$)

I will either behave like A or like B



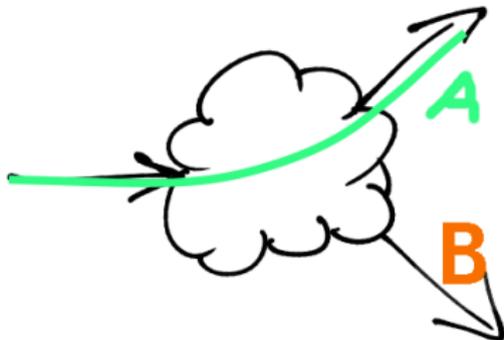
Definition (Branching $A + B$)

You can make me do A or B

Choice

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I will either behave like A or like B



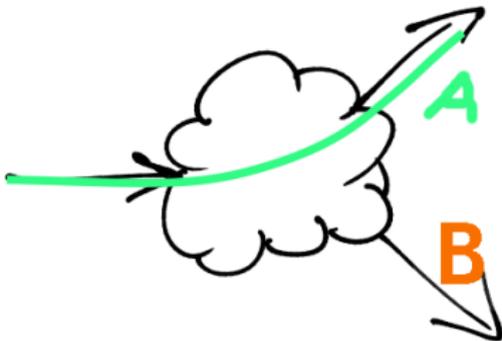
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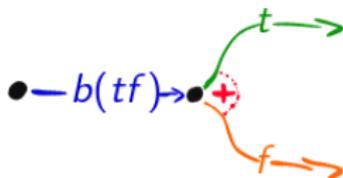
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Choice Examples (I)

- Data Encodings

$$b := \text{True} \quad \stackrel{\text{def}}{=} \quad !b(tf).\bar{t}$$

$$b := \text{False} \quad \stackrel{\text{def}}{=} \quad !b(tf).\bar{f}$$



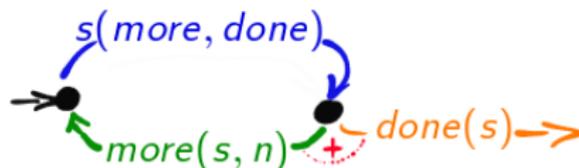
$$\text{If } b \text{ Then } P \text{ Else } Q \quad \stackrel{\text{def}}{=} \quad \bar{b}(\nu tf).(t.P + f.Q)$$

Choice Examples (II)

- Client-Server Conversations

$$\overline{prod}(\nu s).s(\text{more}, \text{done}).\overline{more}(\nu s, 2).$$

$$s(\text{more}, \text{done}).\overline{more}(\nu s, 5).$$

$$s(\text{more}, \text{done}).\overline{done}(\nu s).s(x).\overline{print}\langle x \rangle$$


$$! prod(s).\overline{p_0}\langle 1, s \rangle \quad | \quad ! p_0(t, s).\overline{s}(\nu \text{more}, \text{done}).$$

$$(more(s, n).\overline{p_0}\langle t \times n, s \rangle + done(s).\overline{s}\langle r \rangle)$$

Algebra

Spatial Operators

Parallel Composition $\Gamma_1 \odot \Gamma_2$, Restriction $(\nu x) \Gamma$, ...

Logical Operators

Equivalence \cong , Weakening \leq , Reduction \hookrightarrow , ...

Dynamic Operator

Transition Operator $\Gamma \xrightarrow{\mu} (\Gamma \wr \mu)$.

Semantics (Universal)

Definition (Universal Semantics)

A $(\Gamma; P)$ typed process is *correct wrt. universal semantics*

(" $\Gamma \models_{\mathcal{U}} P$ ") if, for all transition sequences $(\Gamma; P) \xrightarrow{\tilde{\mu}} \searrow (\Gamma'; P')$, the local component of Γ' being $\bigvee_{i \in I} p_{i k_i} \triangleleft \varepsilon_i$: for all $i \in I$ with $k_i \in \mathcal{U}$, $\text{good}_{k_i}(p_i \triangleleft \varepsilon_i, (\Gamma'; P'))$ holds.

Semantics (Existential)

(Abbreviated) Existential Semantics

A typed process $(\Gamma; P)$ is *correct* (" $\Gamma \models P$ "), if \exists a strategy f s.t. For any sequence

$(\Gamma; P) = (\Gamma_0; P_0) \cdots \xrightarrow{\tilde{\mu}_i} \searrow (\Gamma'_i; P'_i) \xrightarrow{f} (\Gamma_{i+1}; P_{i+1}) \cdots$, let (for all i) μ_i be the label of $(\Gamma'_i; P'_i) \xrightarrow{f} (\Gamma_{i+1}; P_{i+1})$.

Then \exists a resource p_k and $n \geq 0$ such that:

- 1 $\forall i : (p_k \triangleleft \text{dep}_{\mathcal{K}}(\mu_i)) \leq \Gamma'_i$
- 2 $\exists \varepsilon : (p_k \triangleleft \varepsilon) \leq \Gamma_n$ and $\text{good}_k(p \triangleleft \varepsilon, (\Gamma_n; P_n))$.

Type System (Universal)

$$\frac{\forall i : \Gamma_i \vdash_{\mathcal{K}} P_i}{\Gamma_1 \odot \Gamma_2 \vdash_{\mathcal{K}} P_1 | P_2} \quad (\text{U-PAR}) \qquad \frac{\Gamma \vdash_{\mathcal{K}} P \quad \Gamma(x) = \sigma}{(\nu x)\Gamma \vdash_{\mathcal{K}} (\nu x : \sigma) P} \quad (\text{U-RES})$$

$$\frac{\forall i : (\Sigma_i; \Xi_{Li} \blacktriangleleft \Xi_{Ei}) \vdash_{\mathcal{K}} G_i.P_i \quad \Xi_E \leq \bigwedge_i \Xi_{Ei}}{(\bigwedge_i \Sigma_i; \bigwedge_{k \in \mathcal{K}} \text{sum}_k(\{p_i\}_i, \Xi_E) \wedge \bigvee_i \Xi_{Li} \blacktriangleleft \Xi_E) \vdash_{\mathcal{K}} \sum_i G_i.P_i} \quad (\text{U-SUM})$$

$$\frac{\Gamma \vdash_{\mathcal{K}} P \quad \text{sub}(G) = p \quad \text{obj}(G) = \tilde{x}}{\left(\begin{array}{l} (p : \sigma; \blacktriangleleft p^m \wedge \bar{p}^{m'}) \quad \odot \\ (; p^{\#(G)} \blacktriangleleft) \quad \odot \\ \text{!if } \#(G) = \omega \quad (\nu \text{bn}(G)) \quad \left(\begin{array}{l} \Gamma \quad \odot \\ \bar{\sigma}[\tilde{x}] \quad \odot \end{array} \right) \\ (; \bigwedge_{k \in \mathcal{K}} \text{prop}_k(\sigma, G, m, m') \blacktriangleleft) \end{array} \right) \vdash_{\mathcal{K}} G.P} \quad (\text{U-PRE})$$

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Properties

- **A** — Activeness

$$\text{prop}_{\mathbf{A}}(G, \sigma, m, m') = \begin{cases} \text{sub}(G)_{\mathbf{A}} & \text{if } \#(G) = \omega \text{ or } m' \neq \star \\ \top & \text{otherwise} \end{cases}$$

- **R** — Responsiveness
- **D** — Determinism (Functionality)
- **I** — Isolation
- **df** — Lock-Freedom
- **N** — Non-Reachability
- ϖ — Termination

Properties

- **A** — Activeness
- **R** — Responsiveness

$$\text{prop}_{\mathbf{R}}(\sigma, G, m, m') = \text{sub}(G)_{\mathbf{R}} \triangleleft \begin{cases} \sigma[\text{obj}(G)] & \text{if } G \text{ is an input} \\ \bar{\sigma}[\text{obj}(G)] & \text{if } G \text{ is an output} \end{cases}$$

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$$\varphi_{\mathbf{D}}(\sigma, G, m, m') \stackrel{\text{def}}{=} \begin{cases} \perp & \text{if } \star \in \{m, m'\} \text{ and } \omega \notin \{m, m'\} \\ \overline{\text{sub}(G)}_{\mathbf{D}} & \text{otherwise} \end{cases}$$

$$\varphi_{\mathbf{D}}(\{p_i\}_i, \Xi) \stackrel{\text{def}}{=} \begin{cases} \perp & \text{if } \Xi \text{ has concurrent environment } p_i \\ \top & \text{otherwise} \end{cases}$$

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Universal Soundness

- Based on transition sequences?
Semantic Predicates aren't transition based! (or are they?)
- Based on contextual semantics?
“ $\Delta_1 \triangleleft \Delta_2 \models P$ if $\forall Q$ s.t. $\Delta_2 \vdash Q: \Delta_1 \models P \mid Q$.”
The definition is circular!
- Implicit definition?
“The set of correct typed processes is the largest that satisfies the above”
There are many solutions!
- Stricter implicit definition?
“The set of correct typed processes is the intersection of all those that satisfy the above”
The intersection is empty!
- To be continued . . .

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There are many solutions!
- Stricter implicit definition?
“The set of correct typed processes is the intersection of all those that satisfy the above”
The intersection is empty!
- To be continued . . .

Universal Soundness

- Based on transition sequences?
Semantic Predicates aren't transition based! (or are they?)
- Based on contextual semantics?
“ $\Delta_1 \triangleleft \Delta_2 \models P$ if $\forall Q$ s.t. $\Delta_2 \vdash Q: \Delta_1 \models P \mid Q$.”
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Existential Soundness

Structural Liveness Strategies

$$\rho ::= \pi\delta \quad | \quad \mathfrak{l} \quad | \quad \dots$$

$$\delta ::= \div \rho \quad | \quad [s]$$

$$\pi ::= (\mathfrak{l}|\rho) \quad | \quad (\mathfrak{l}|\bullet) \quad | \quad (\bullet|\rho)$$

$$s ::= p_1 + p_2 + p_3 \dots$$

\mathfrak{l} : Guard reference

\bullet : Environment

$(\mathfrak{l}|\rho)$: Make \mathfrak{l} and ρ communicate.

Future Work

- Generic Universal Soundness Proof
- Recursivity and **B**ounded Channels.
- Channel Type Reconstruction.
- Software Implementation.

▶ [Link to Appendices](#)